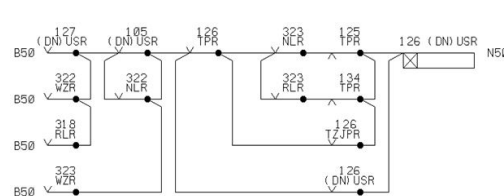




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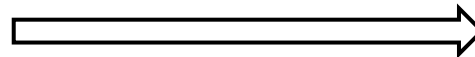
# Evolution of Standards for High-Integrity Software in Railways

Roger Short



QR2 if R2 a / Route label and availability  
P1 crf, P2 cnf / Points test  
U10-AB f, U3-BC f / Directly opposing route(s) test  
then R2 s / Route setting  
U3-CB1, U9-CA1, U10BA1, / Sub-route locking  
11-BA1 U12-BA1  
P1 cr, P2 cn / Points controlling  
S1 clear bpull / Signal clearing

From this



To this

# Introduction



BS EN 50128:2001

**Railway applications. Communications, signalling and processing systems. Software for railway control and protection systems**

Published: 15 May 2001 · Withdrawn: 31 Jul 2011

BS EN 50128:2011+A2:2020  
Incorporating corrigendum February 2014



BS EN 50716:2023

**Railway applications - Communication, signalling and processing systems - Software for railway control and protection systems**

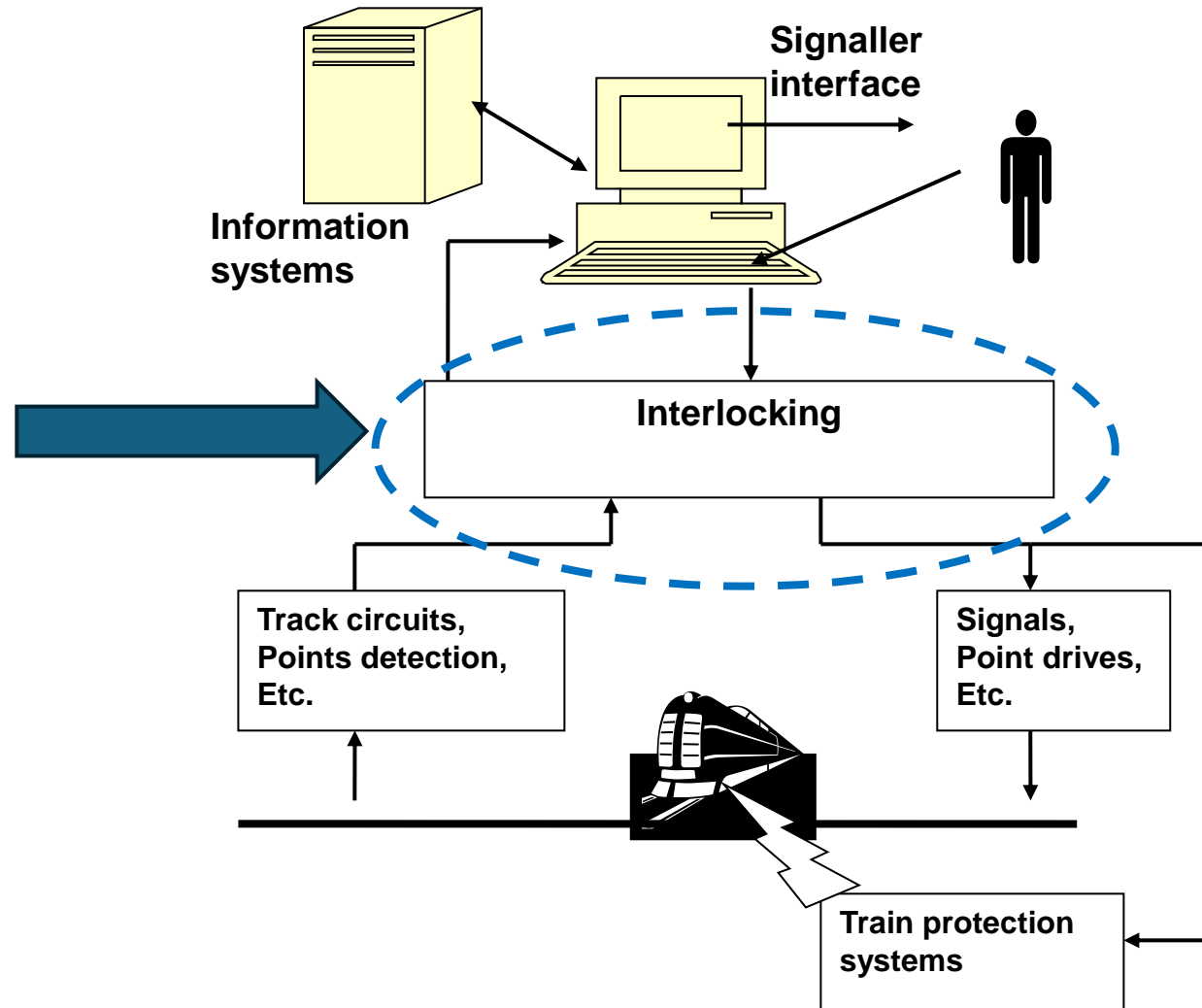


This presentation outlines how standards for high integrity software in railways have evolved, starting from the earliest applications in railway signalling

**Railway Applications — Requirements for software development**

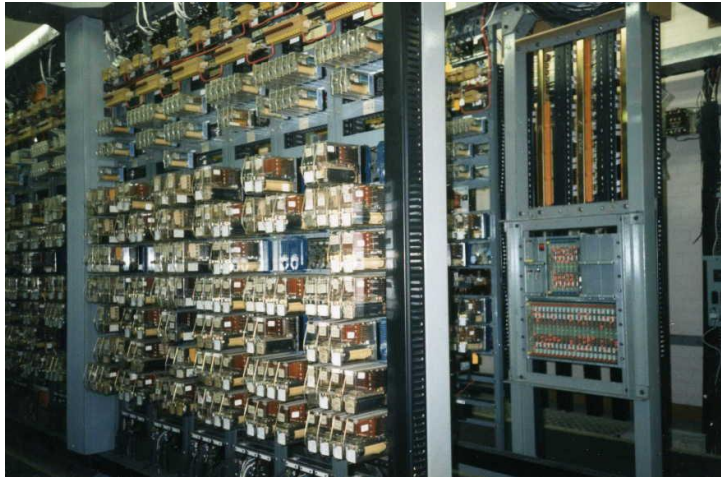
# The Signalling System

An interlocking is a system which allows a train to proceed only when all relevant conditions are safe.

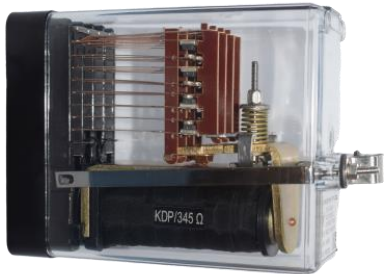


# Interlocking Technology

Mid 20<sup>th</sup> Century



Equipment Room



Relay



- Less equipment
- Smaller buildings
- Less cabling
- Less installation work
- Quicker and cheaper application design was hoped for (“it’s only software”) but achievement questionable.

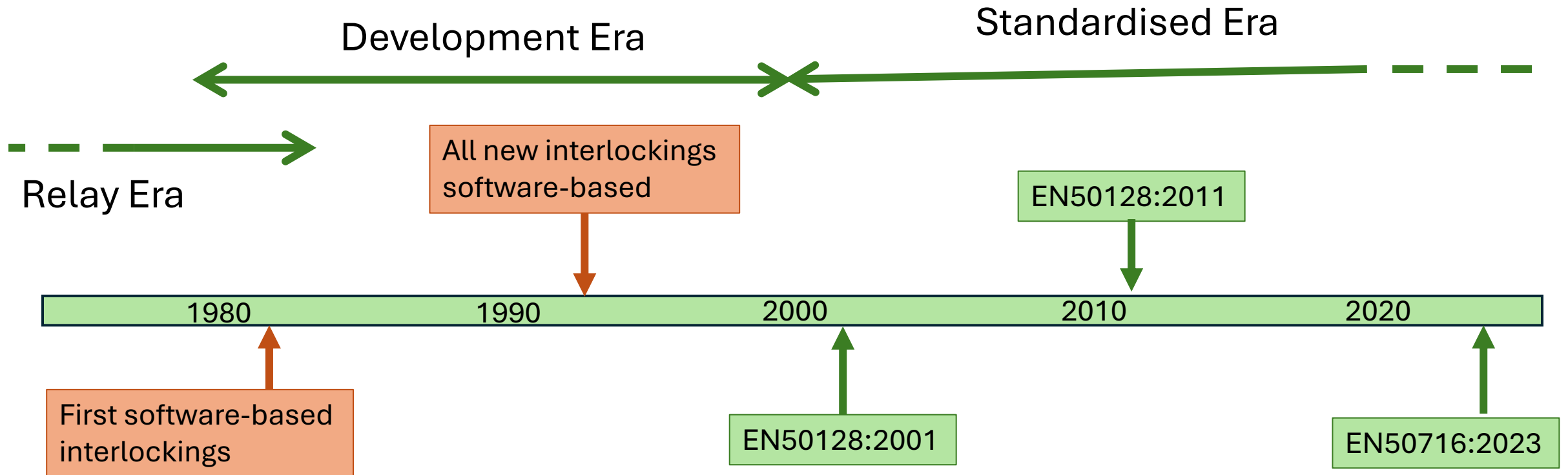
1980s onwards



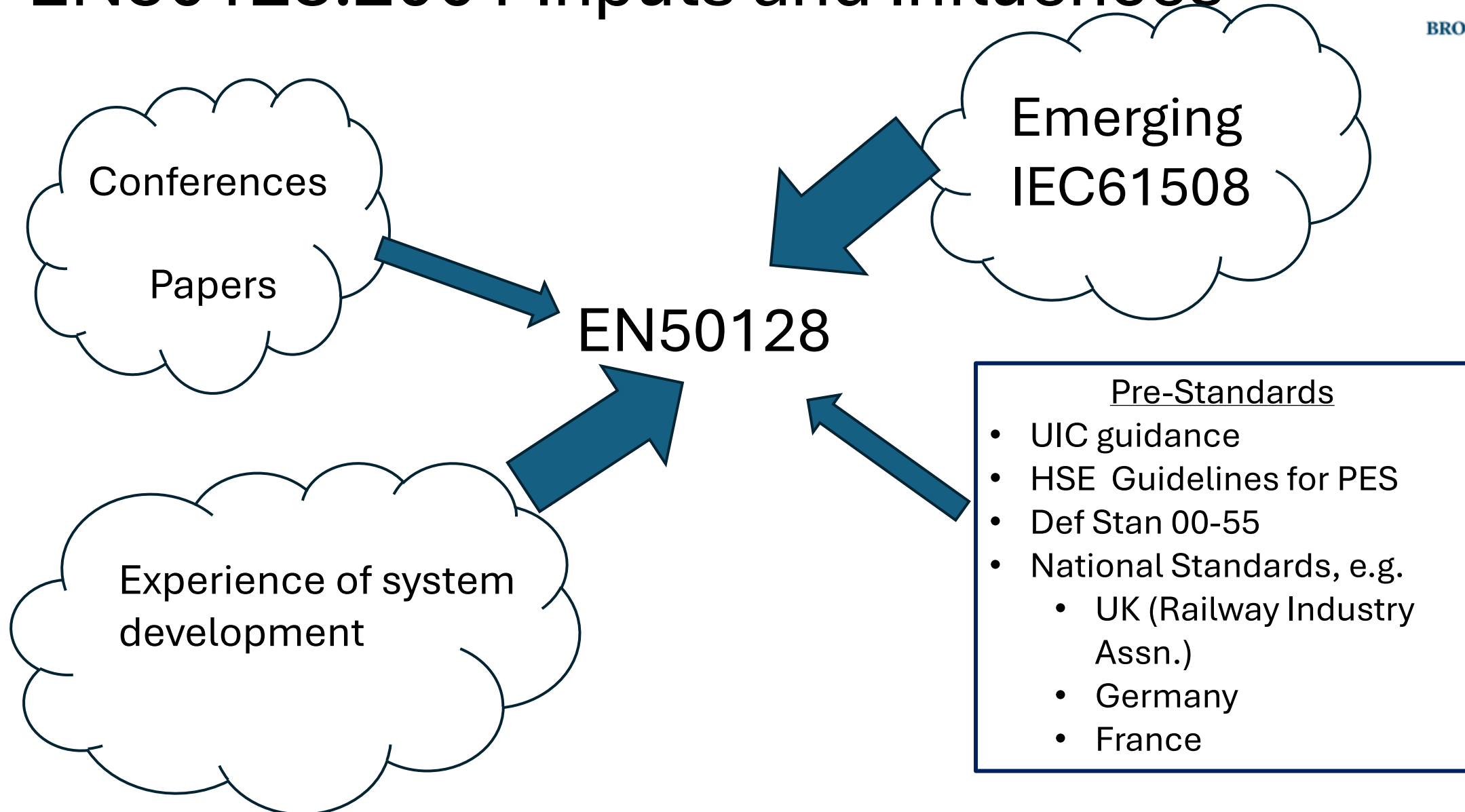
Lineside object controller

Central Interlocking

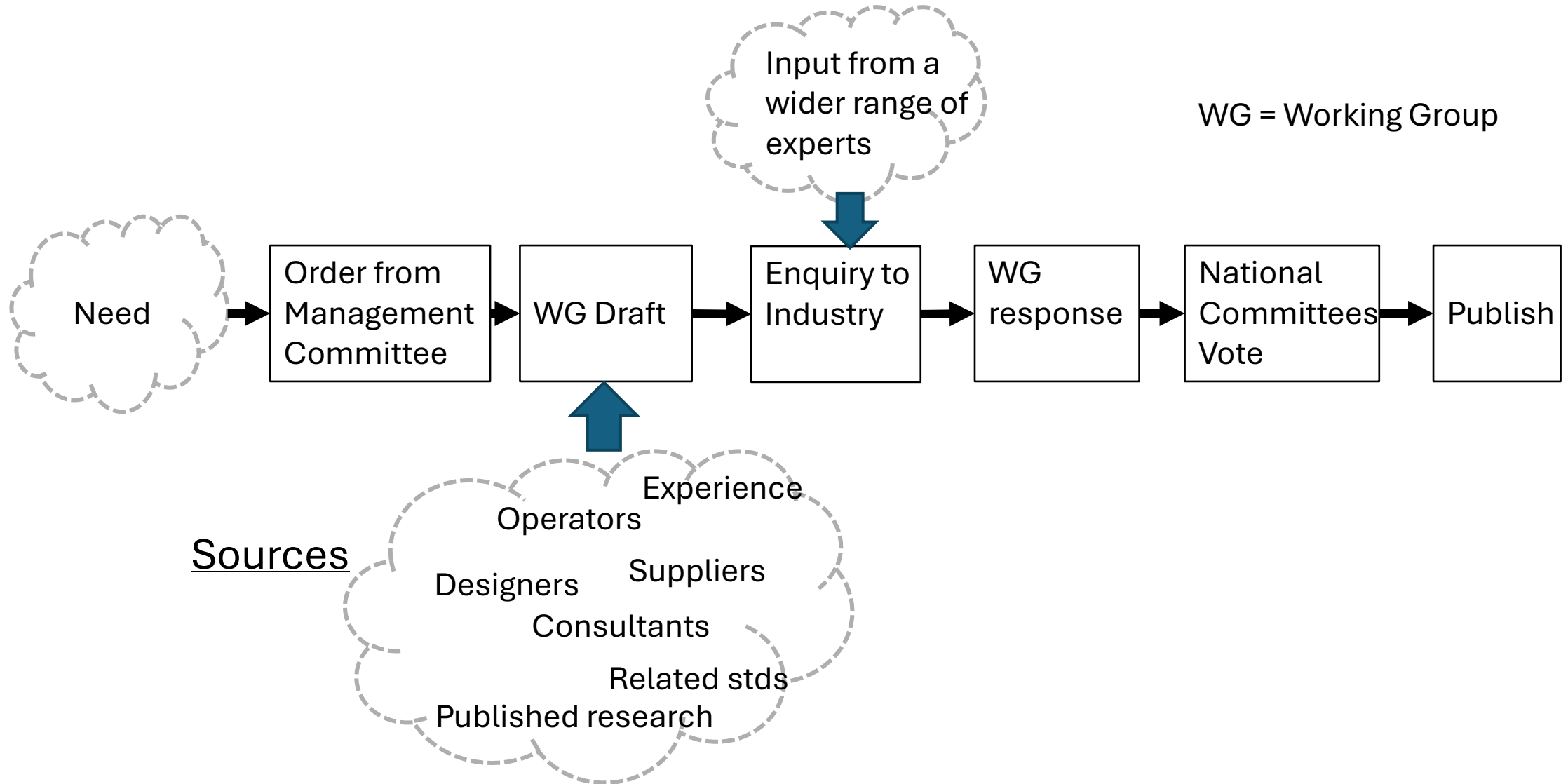
# Evolutionary Timeline



# EN50128:2001 Inputs and Influences



# CENELEC Process for Standards



# Working Groups

- Experts nominated by national standards organisations, e.g. BSI, volunteered by their employers.
- Usually act as individuals rather than national delegates.
- Can be multiple experts per country.



Expert being volunteered to a WG

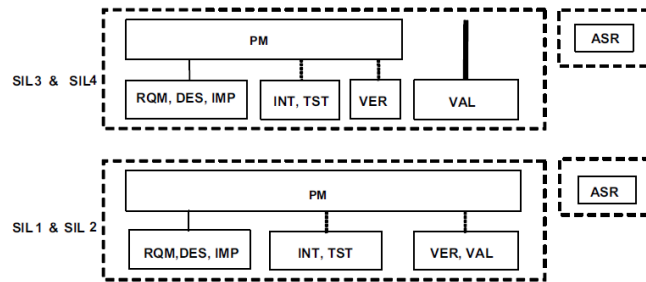


# Essence of EN50128



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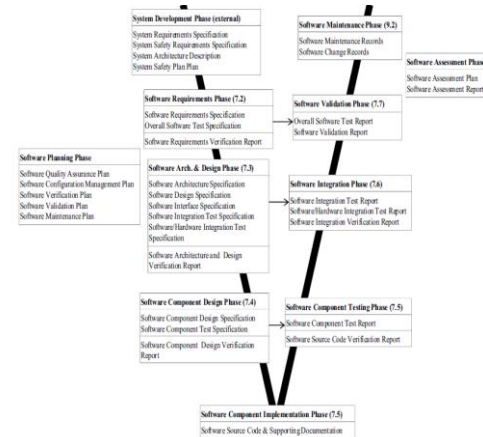
## Safety Management



Organisation



Documentation



Lifecycle

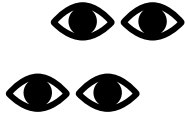
## Techniques and Measures

- Techniques which reduce the probability of software defects being introduced, e.g. improved programming languages, structured programming;
- Techniques which can show that the software will behave correctly, e.g. white box testing, symbolic execution;
- Techniques which detect anomalies but which do not show that software will behave correctly, e.g. structural analysis, data flow analysis

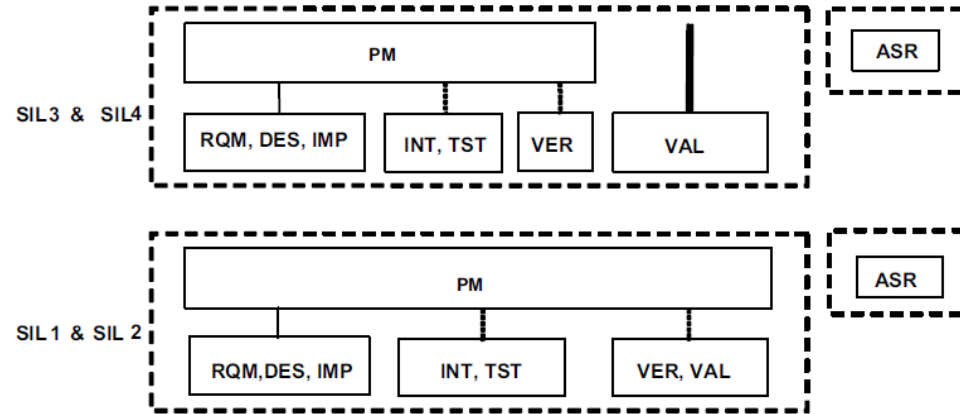

# Examples of Requirements for Safety Management

## Organisation – Roles and Responsibilities

Important to ensure independence of roles with safety responsibilities, e.g. Verifier independent of Designer



**Independence of Roles**  
Sometimes called the “4 eyes principle” but 2 brains is better

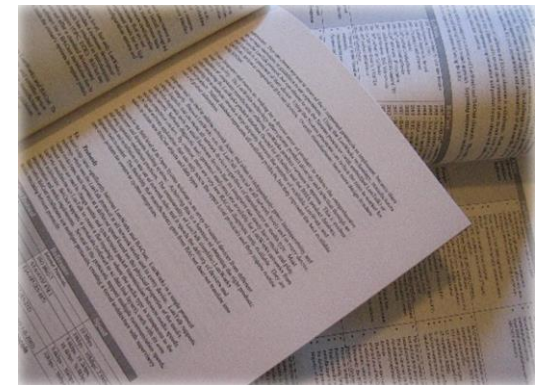


## Documentation

Many specific documents are required.

Do not despise documentation. System development and safety assurance are **socio-technical** processes. Without good documentation the **SOCIO** part won't work and the **TECHNICAL** part will go wrong!

- Plans
- Specification
- Designs
- Analyses
- Reports



# Techniques and SIL

20+ tables of recommended techniques and measures.

To claim that a required SIL has been achieved, all relevant approved combinations must be used.

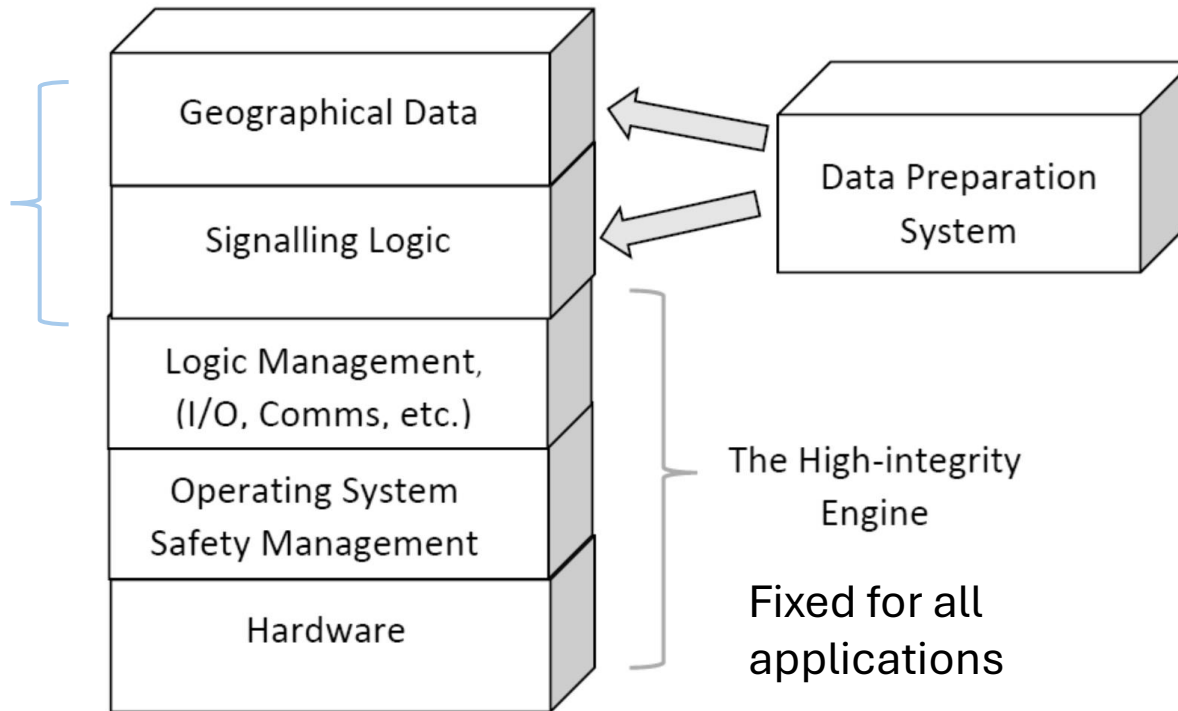
**Note:** In all versions of the standard, the recommendations for SIL1 and SIL 2, and for SIL3 and SIL4 are always the same

Table A.5 – Verification and Testing (clause 11)

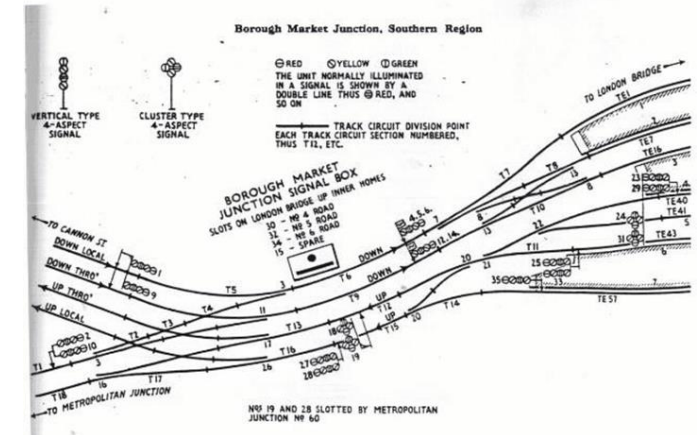
TECHNIQUE/MEASURE	Ref.	SWSIL 0	SWSIL 1	SWSIL 2	SWSIL 3	SWSIL 4
1. Formal Proof	B.31	-	R	R	HR	HR
2. Probabilistic Testing	B.47	-	R	R	HR	HR
3. Static Analysis	dt8	-	HR	HR	HR	HR
4. Dynamic Analysis and Testing	dt2	-	HR	HR	HR	HR
5. Metrics	B.42	-	R	R	R	R
6. Traceability Matrix	B.69	-	R	R	HR	HR
7. Software Error Effect Analysis	B26	-	R	R	HR	HR
<p>Requirements</p> <p>1. For Software Safety Integrity Level 3 or 4, the approved combinations of techniques shall be:</p> <p>a) 1 and 4  or b) 3 and 4  or c) 4, 6 and 7</p> <p>2. For Software Safety Integrity Level 1 or 2, the approved combinations of techniques shall be:</p> <p>a) 1  or b) 3 and 4  or c) 4</p>						

# Configuration Logic and Data

Repeated for each application



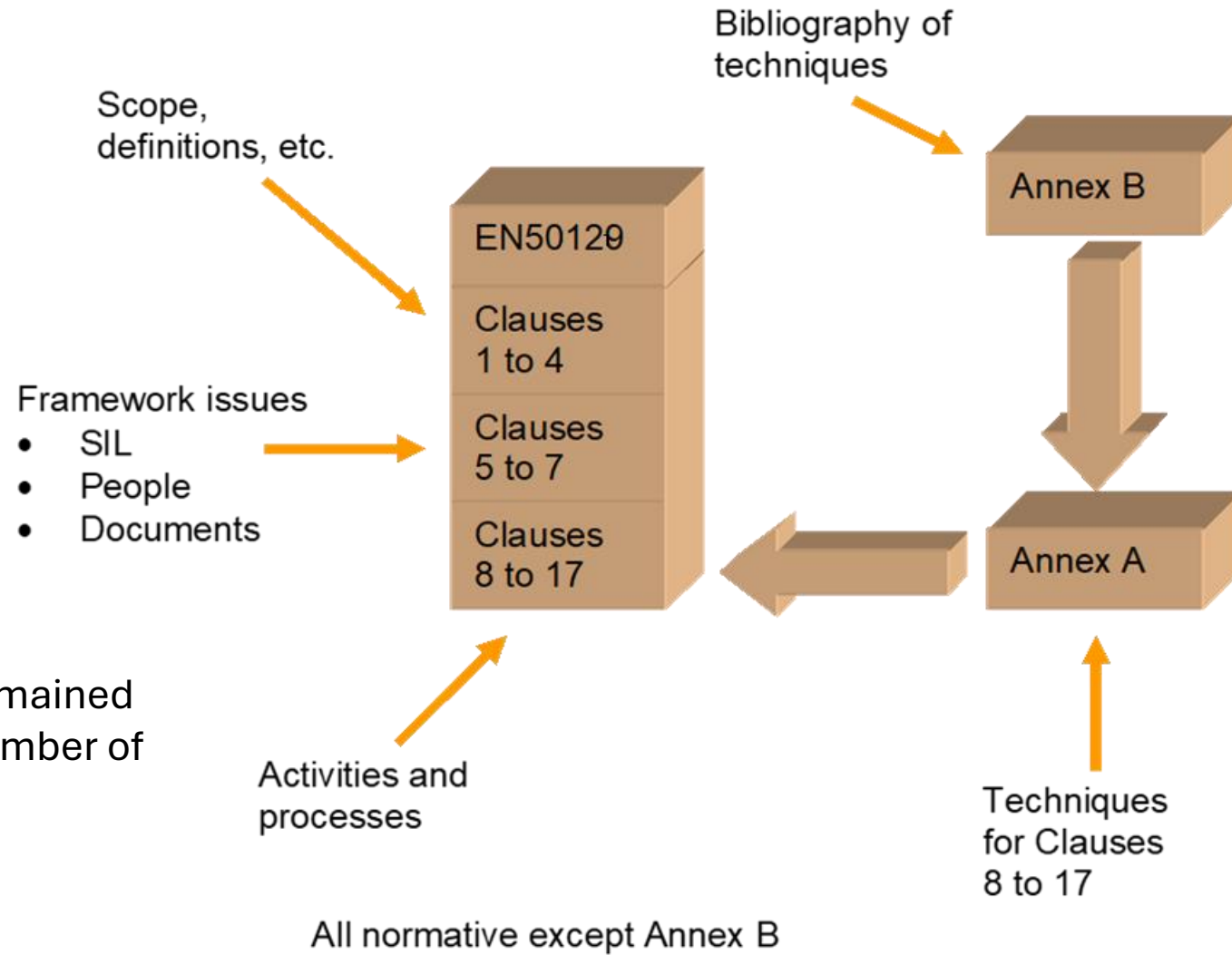
Signal interlocking systems need to be configured to the area under control



Area under control

All versions of the Standard include a chapter on development of application logic and data

# Structure of EN50128



The structure has remained constant, but the number of annexes has grown

All normative except Annex B

# Changes in EN50128:2011



## 2001 version

Personnel and responsibilities.....	17
6.1 Objective.....	17
6.2 Requirements.....	18

## 2011 version

5 Software management and organisation.....	18
5.1 Organisation, roles and responsibilities.....	18
5.2 Personnel competence.....	21

- Organisational requirements expanded
- Key responsibilities more fully defined
- Competence requirements now included

Includes requirements for competence



**Annex B**  
(normative)

**Key software roles and responsibilities**

# Changes in EN50128:2011



- Additional requirements for documentation, including generic requirements for document quality.
- Additional generic requirements for software assurance.
- Generic requirements for support tools.
- SIL0 becomes Basic Integrity.

## 2001 version

7	Life cycle issues and documentation .....	19
7.1	Objectives .....	19
7.2	Requirements .....	19

## 2011 version

5.3	Lifecycle issues and documentation .....	22
6	Software assurance .....	24
6.1	Software testing .....	24
6.2	Software verification.....	26
6.3	Software validation .....	28
6.4	Software assessment .....	29
6.5	Software quality assurance.....	31
6.6	Modification and change control.....	33
6.7	Support tools and languages .....	34

# EN 50657:2017 – Software for Rolling Stock



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- Effectively EN 50128:2011 adapted to rolling stock applications.
- Changes mainly concerned with terminology.
- Structure and technical content transposed from EN 50128.
- Minor technical changes.





# Changes in EN50716:2023

- Merged with EN 50657:2017

- Role independence requirements simplified



Various special cases and relaxations dropped

- Additional guidance on:

- Alternative Lifecycles

- Modelling

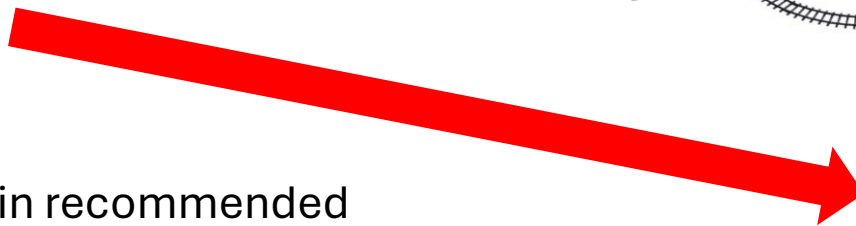


- AI/ML



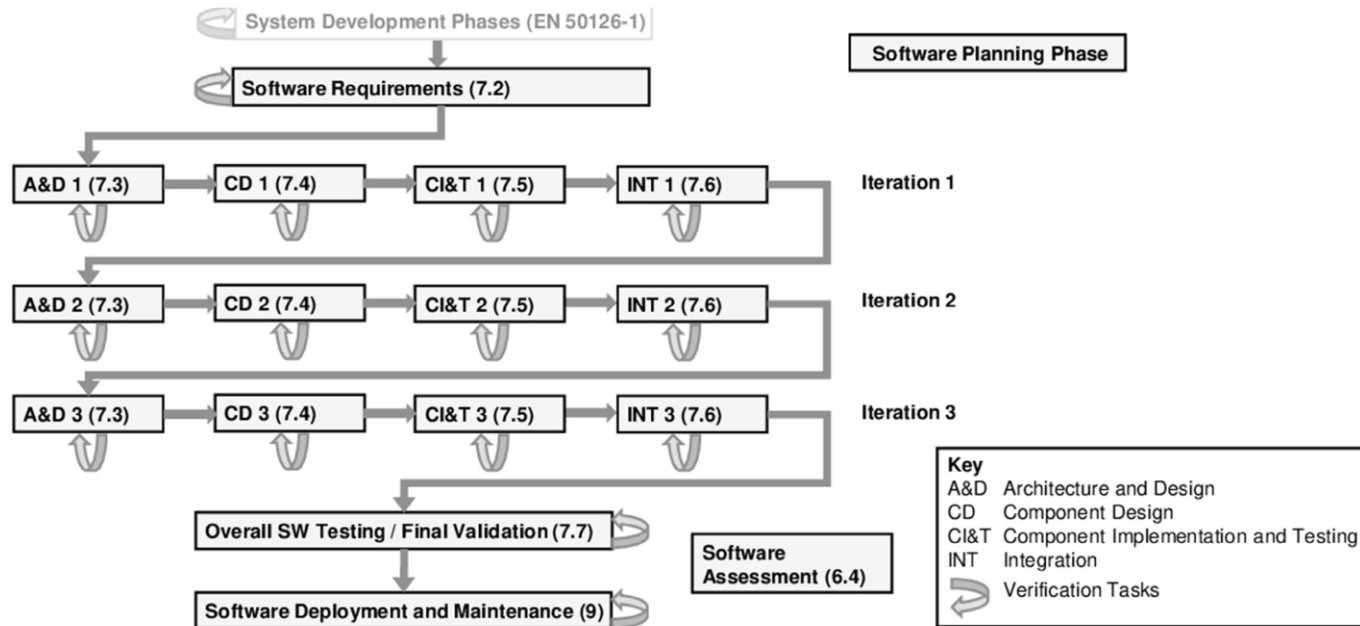
**Not this sort!**

Also detailed changes in recommended techniques, e.g. recommending properties of programming languages rather than specific languages.



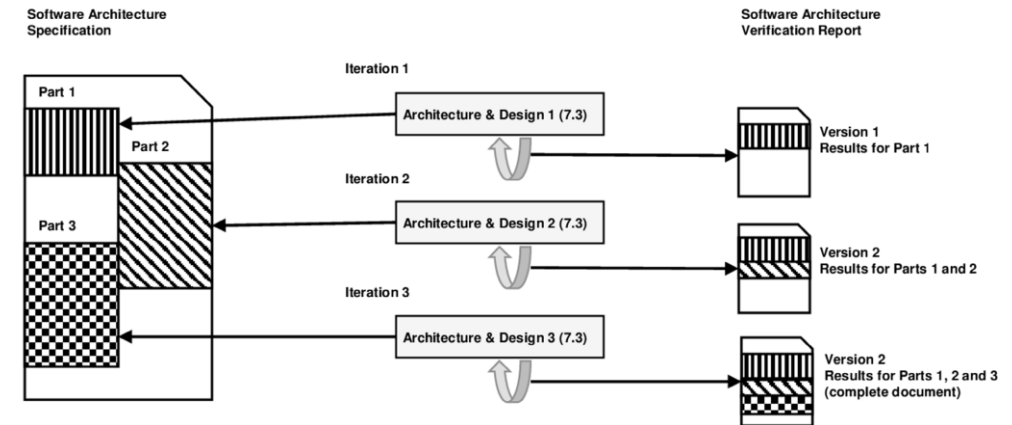
Caused some alarm in the AI community

# Lifecycles



Example of Iterative Lifecycle

Guidance is given on iterative alternatives to the classic linear V lifecycle



Example of iterative development of a work product

# Modelling

“A model is a logical representation aimed at developing, understanding, communicating, or explaining aspects of a system, entity, or process.”

The annex provides guidance on how to apply the requirements of the standard when modelling is used in software development.

Table C.2 — Component implementation and testing typical adaptation for modelling

SUBCLAUSES	TYPICAL ADAPTATION FOR MODELLING
7.5.4.2 The size and complexity of the developed source code shall be balanced.	7.5.4.2 The size and complexity of the developed model shall be balanced.
7.5.4.3 The Software Source Code shall be readable, understandable and testable.	7.5.4.3 The model shall be readable, understandable and testable.
7.5.4.4 The Software Source Code shall be placed under configuration control before the commencement of documented testing.	7.5.4.4 The model shall be placed under configuration control before the commencement of documented testing.

During the years between 1980 and the appearance of the first version of the standard in 2001, much work was published on representations (models as defined above by EN50716) which would have alleviated some of the problems of system development. The delay in their recognition is surprising.

# AI and Functional Safety – State of the Art



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PD ISO/IEC TR 5469:2024



Artificial intelligence — Functional safety and AI systems

AI technology Class III covers applications which would be classed as SIL1 – SIL 4 in EN 50716

AI Technology Class => AI application and usage level	AI technology Class I	AI technology Class II	AI technology Class III
Usage Level A1 (1)	Application of risk reduction concepts of existing functional safety International Standards possible	Appropriate set of requirements (3)	At the time of writing this document no appropriate set of properties with related methods and techniques is known to achieve sufficiently reduction of risk
Usage Level A2 (1)		Appropriate set of requirements (3)	
Usage Level B1 (1)		Appropriate set of requirements (3)	
Usage Level B2 (1)		Appropriate set of requirements (3)	
Usage Level C (1)		Appropriate set of requirements (3)	
Usage Level D (2)	No specific functional safety requirements for AI technology, but application of risk reduction concepts of existing functional safety International Standards		

AI Classification Table from TR 5469

# AI/ML Gaps in EN50716

